



北京 国家会议中心 2018年 9月10-12日 2018.hexagonchina.com.cn



自动化监测与人工监测的桥梁 与隧道监测

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國際測量師聯合會FIG 2003-2006 副會長

香港測量師學會會長 1997/98

2016年以来NZIS香港分會主席



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项目背景



中环湾仔绕道及东区走廊通道 (CWB)

是香港岛北岸的一条战略道路,旨在 纾缓Gloucester现有道路- Harcourt 道- Connaught中心走廊的交通拥堵。 在法定程序中重申了这一需要,并在 公众参与过程中得到支持。

项目管理:

公路部门

咨询工程公司:

AECOM 亚洲有限公司.

预算项目成本:

港币360 亿元

建筑开工日期:

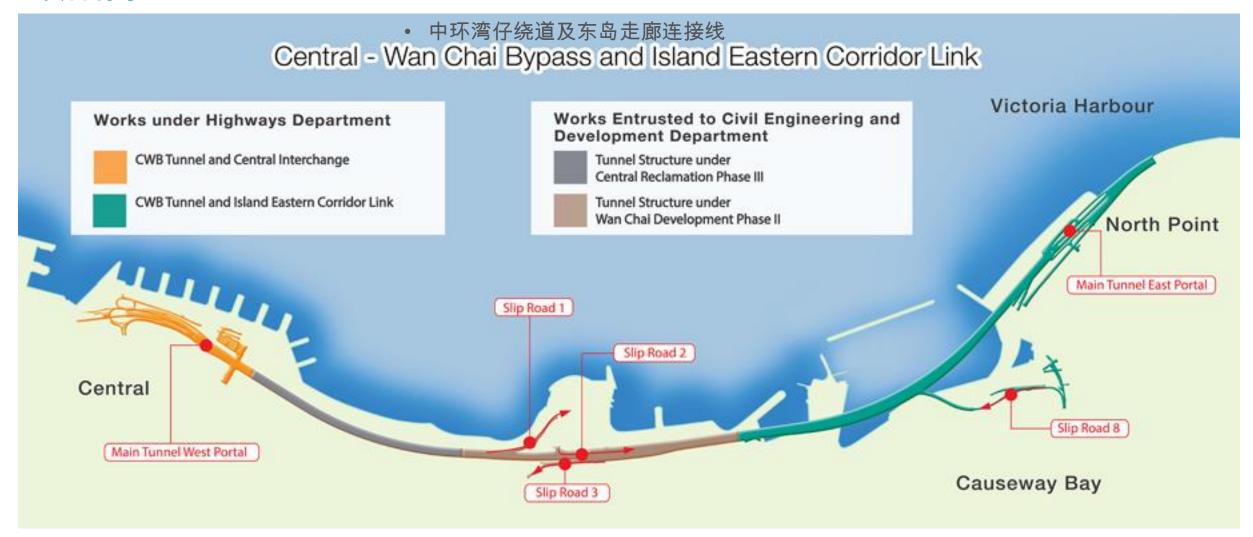
2009年12月

预计投产日期:

2018年末 / 2019年第一季度



项目背景





ADMS 测量 - 设站点 1 (临时设置)

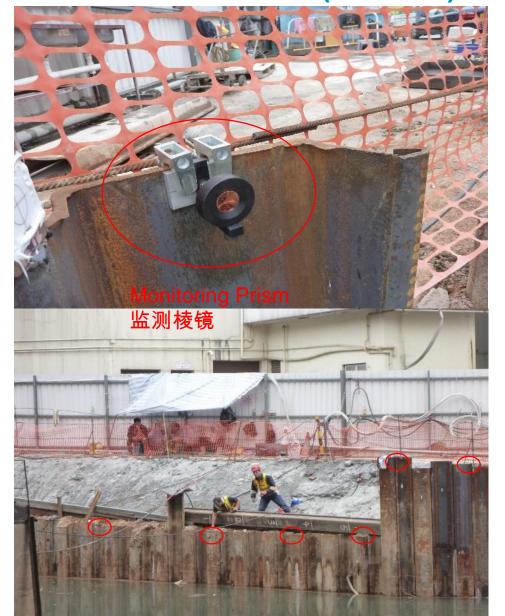
We have Computer, UPS, communication device, Geomos Monitor and Geomos Analysis inside the box

我们使用了计算机、UPS\通讯设备、GeoMoS的监测器和分析器。都安装在这个箱子里。





ADMS 测量 - 设站点 1 (临时设置)







ADMS 测量 -设站点 1 (永久设置)

This is Permanent Setup 这是永久设站点



This is Temporary Setup 这是临时设站点



ADMS 测量 -设站点 1 (永久设置)













We have Computer, UPS, Geomos Monitor and Geomos Analysis inside the box

在箱子里安装了 电脑、UPS、 GeoMoS的监测 器和分析器















海 克 斯 康 HEXAGON









ADMS 测量 - 设站点 5 (CHT1)







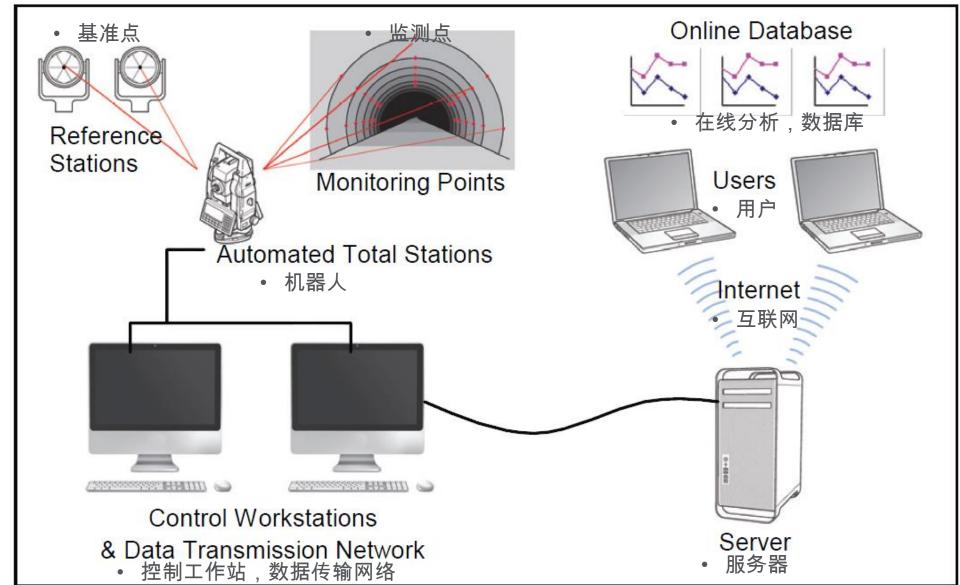
Reference Prism 基准棱镜







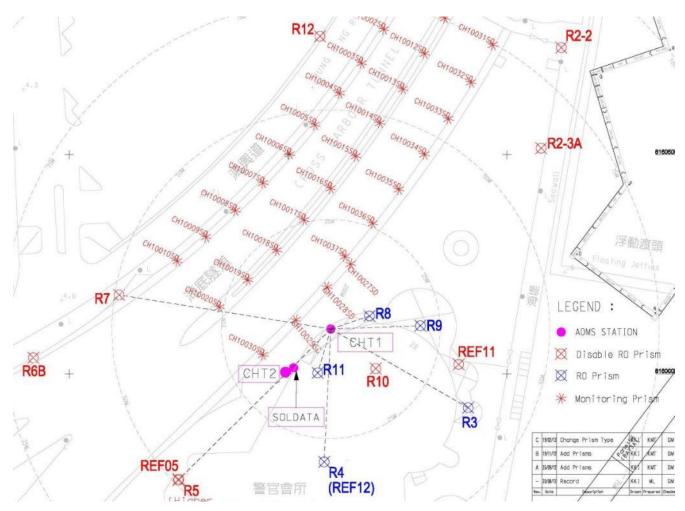
ADMS 测量 - 设站点5 (系统组成)





ADMS 测量 - 设站点 5 (网络设计)

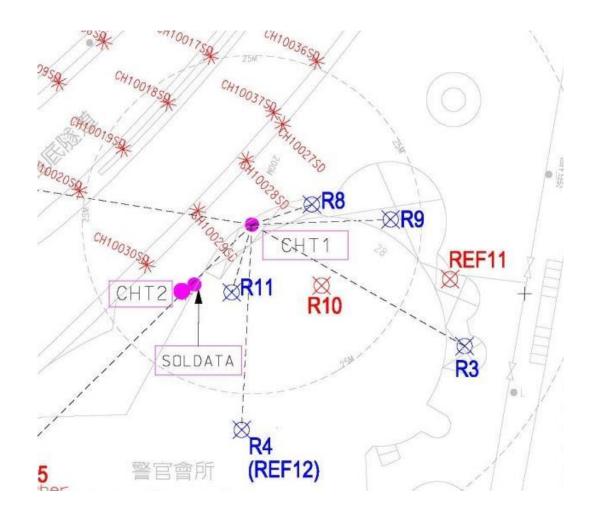
- 最少5个点
- 等边三角形,
- 角度大小: 大于30°; 小于120°
- 覆盖监测区域





ADMS 测量 - 设站点 5 (自由设站)

• 从无坐标的站点,测量坐标系中的已知点





ADMS 测量 - 设站点 5 (独立检查)

- 每月核实监测数据
 - →对ADMS产生的数据进行核对

- 使用常规测量技术进行人工检查
 - 导线
 - 水准测量



ADMS 测量 - 设站点 5 (质量控制)

- 维护/年度校准
- 基准和监测棱镜的清洗
- 全站仪标定
 - 补偿器指标误差
 - 垂直指标误差
 - 水平准直误差
 - ATR水平角和ATR竖直角



I, t Compensator longitudinal and transversal index errors

Vertical index error, related to the standing axis

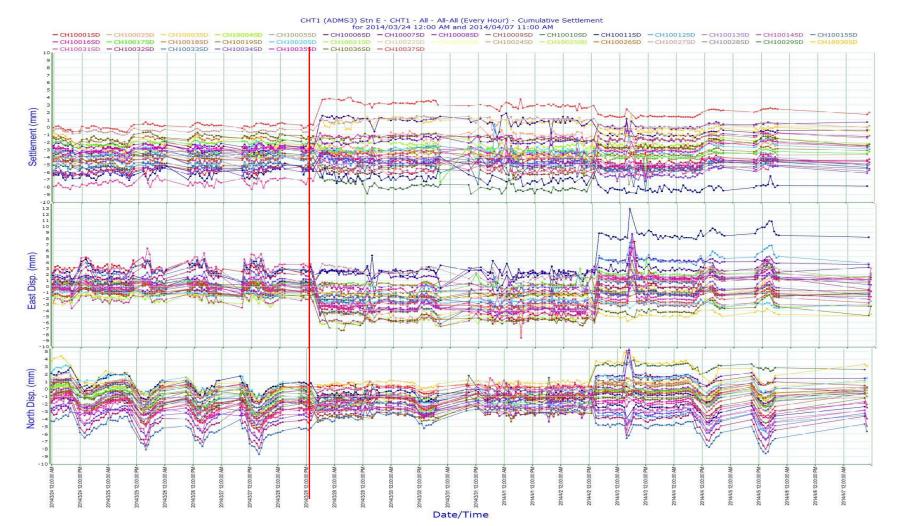
Horizontal collimation error, also called line of sight error

ATR Hz ATR zero point error for horizontal angle option

ATR V ATR zero point error for vertical angle option



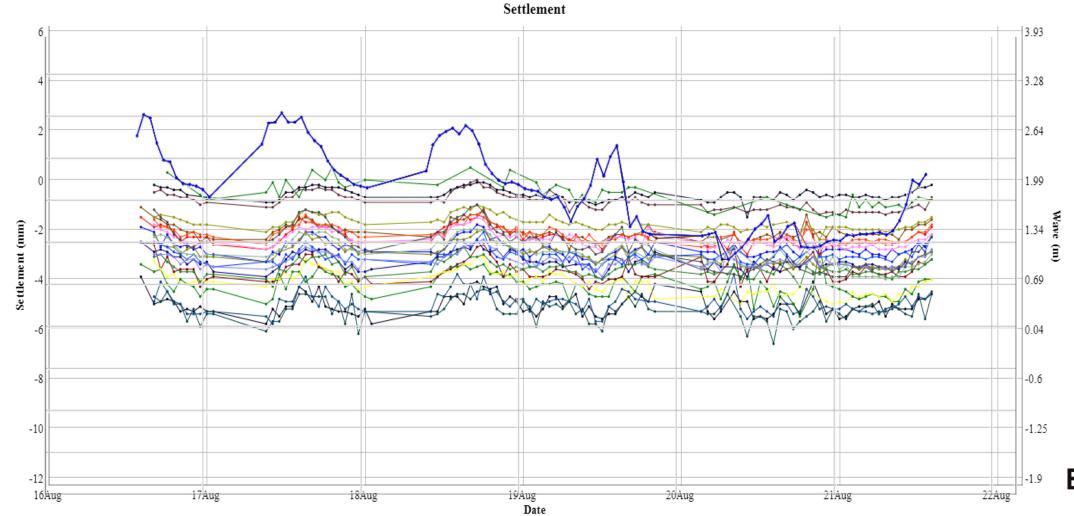
• 情况: 增加 PVC 罩子







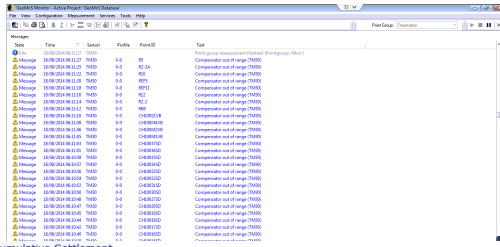
• 情况: 温度影响





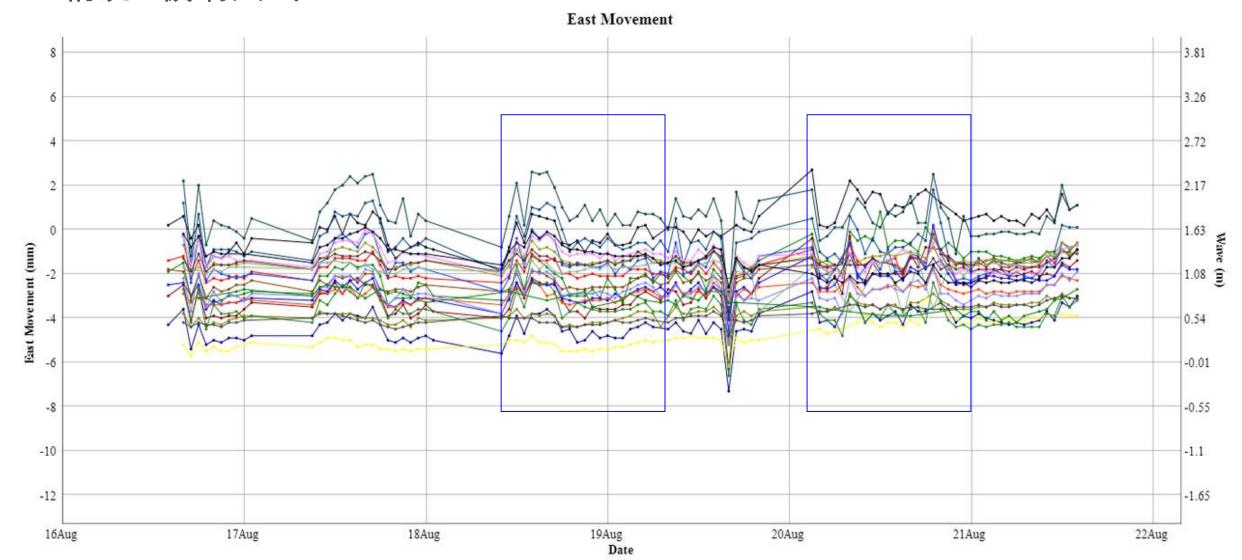
• 情况:

补偿器超限

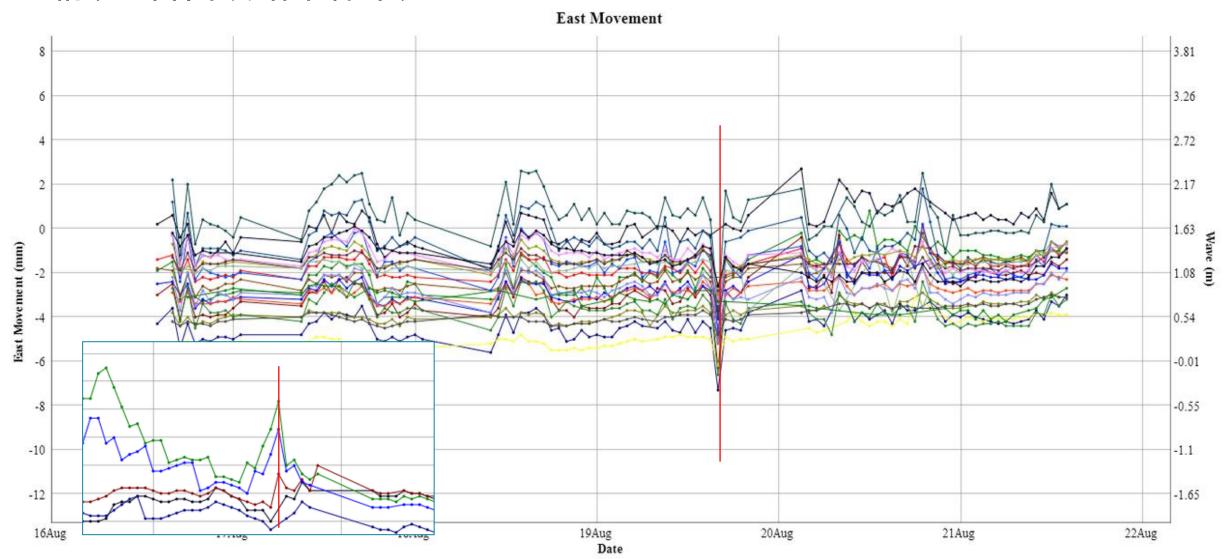


CHT1 (ADMS3) Stn E - CHT1 - All - All-All (Every Hour) - Cumulative Settlement for 2014/08/04 12:00 AM and 2014/08/18 11:00 AM - CH10001SD - CH10002SD - CH10003SD - CH10004SD - CH10005SD - CH10005SD - CH10007SD - CH10009SD - CH10011SD - CH10011SD - CH10013SD - CH10014SD - CH10015SD - CH10016SD - CH10017SD - CH10019SD - CH10019SD - CH10020SD - CH10021SD - CH10022SD - CH10022SD - CH10024SD -CH10025SD -CH10026SD -CH10027SD -CH10028SD -CH10029SD -CH10030SD CH10031SD - CH10032SD - CH10033SD - CH10034SD - CH10035SD - CH10036SD - CH10037SD Settlement (mm) Date/Time

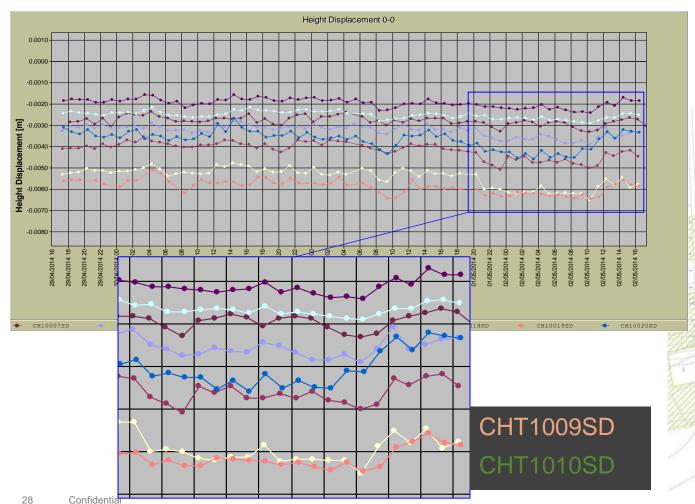
• 情况: 极端天气



• 情况: 自由设站条件不足



• 情况: 采空区涌水量

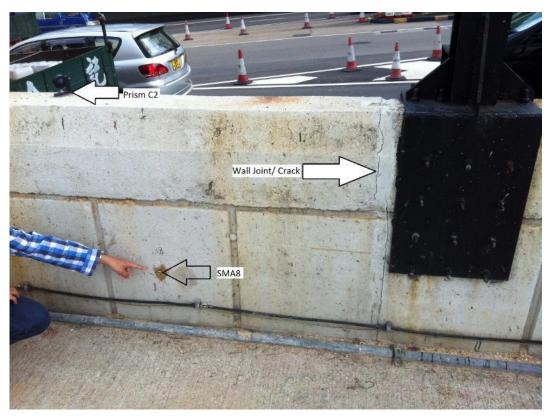






人工测量检查







人工测量检查









人工测量检查





4圆4弧精密测量

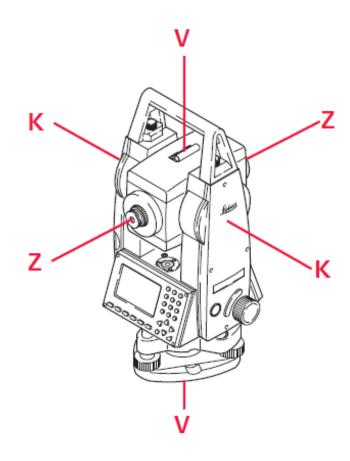
▶ 盘左& 盘右测量

▶ 4 圆 4 弧 (即在不同测回间配置水平度盘的方法)

▶ 水平角闭合(水平角度闭合方法)



4圆4弧精密测量-盘左盘右观测

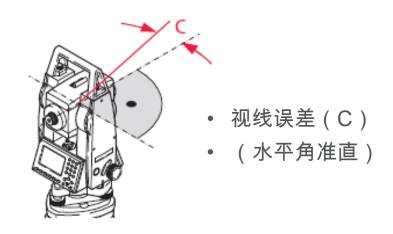


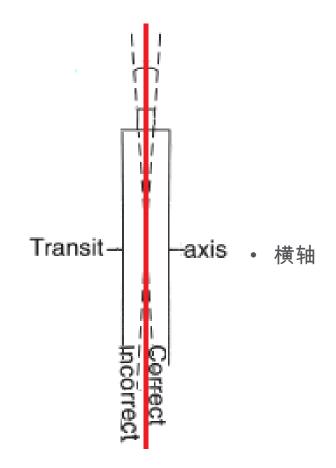
▶消除误差

- a)视线Z Z垂直于横轴 K K
- b)横轴KK垂直于垂直轴V V
- c)垂直轴V V严格垂直
- d)竖盘在天顶精确读零



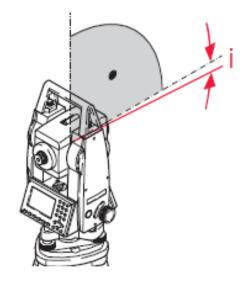
4圆4弧精密测量-准直误差



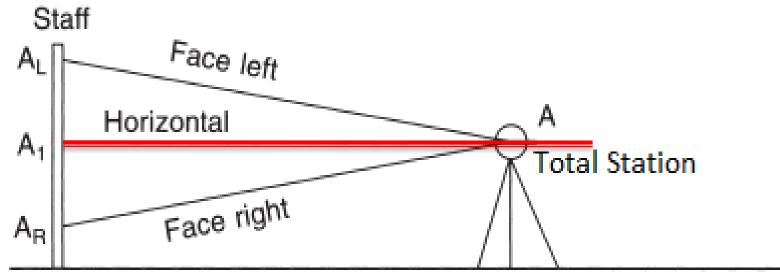




4圆 4 弧精密测量 - 高度指数误差



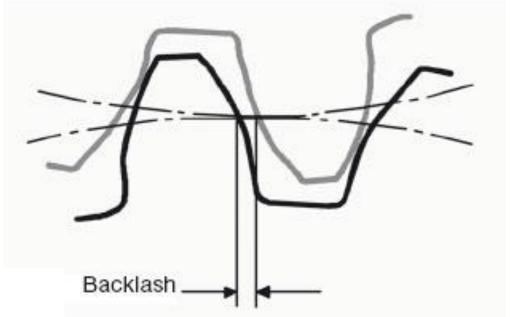
- 高度指数误差(i)
- 竖盘指标

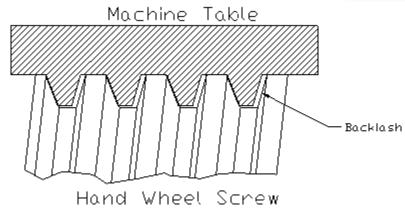




4圆 4 弧精密测量 - 齿隙

▶齿隙是在一对齿轮之 间形成的间隙。







4圆 4 弧精密测量 - 齿隙

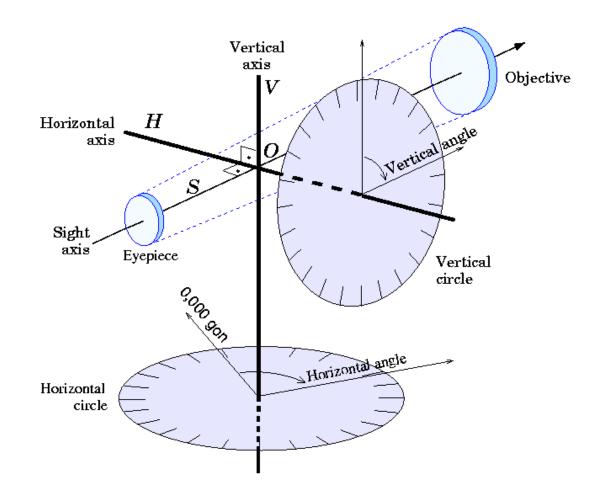
▶ 盘左观察:总是顺时针方向转动

▶ 盘右观察:总是逆时针方向转动.



- 消除度盘刻度误差
- ▶ 计算 S.Dev

$$\sigma = \sqrt{\frac{1}{N} \sum_{i=1}^{N} (x_i - \overline{x})^2}$$

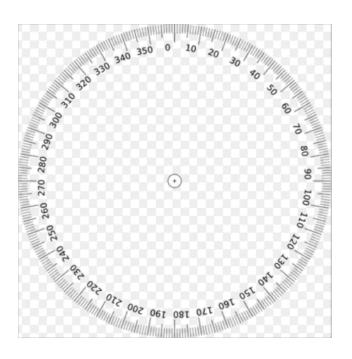




4圆4弧精密测量(配置水平度盘)

▶ 盘左: 盘右:

000-00-00	180-00-00



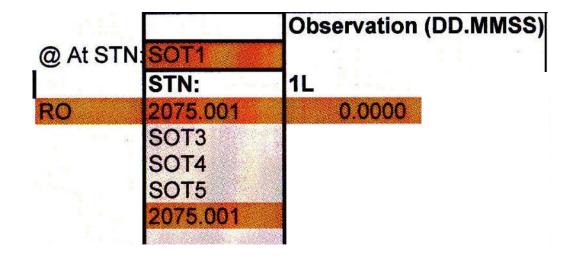


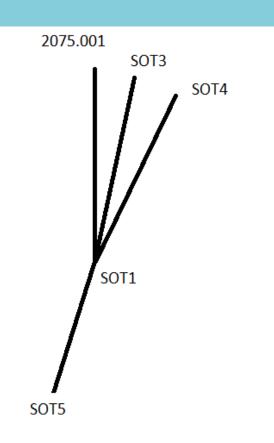
4圆 4 弧精密测量 - 水平角闭合

确保全站仪在观测过程中没有被移动。

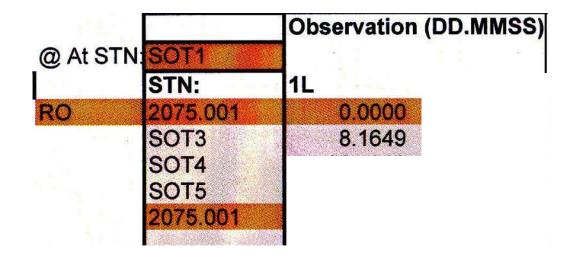
▶检查它是否是360°

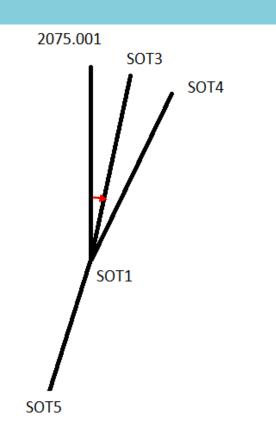




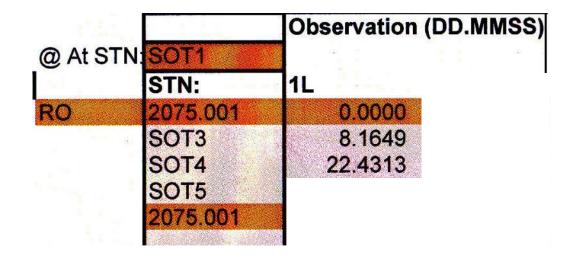


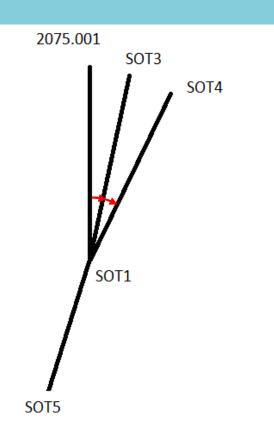




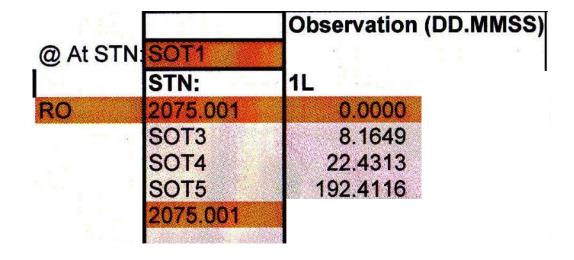


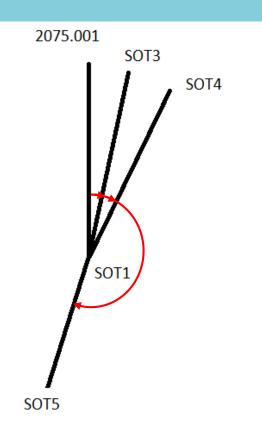




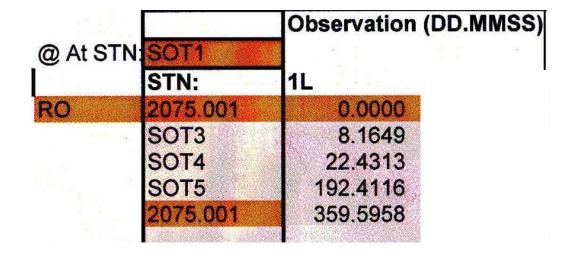


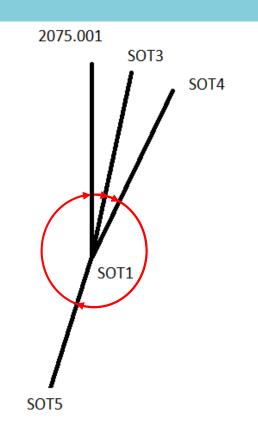




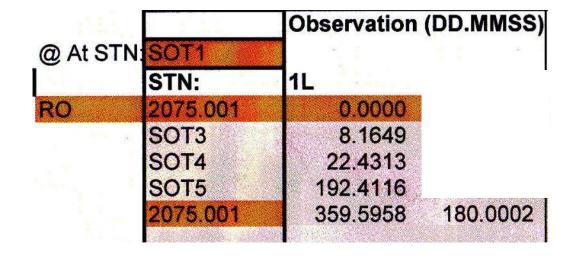




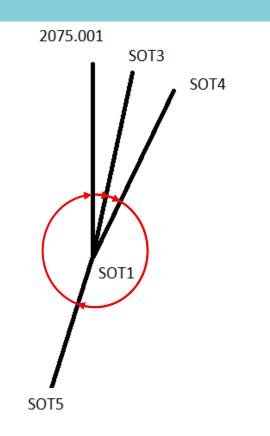




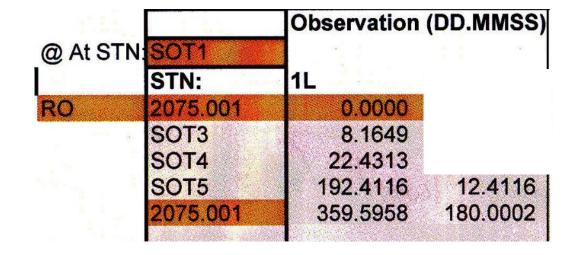




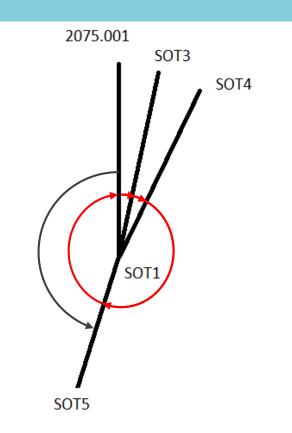
• 盘右,逆时针观测



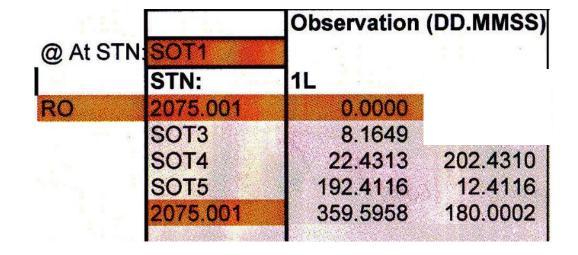




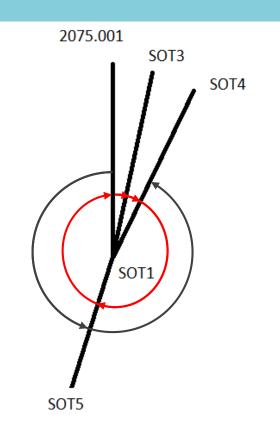




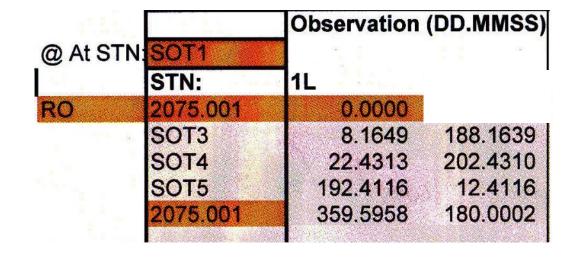




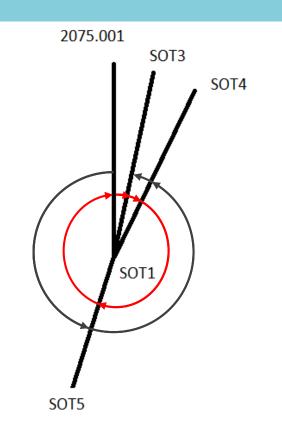
• 盘右,逆时针观测



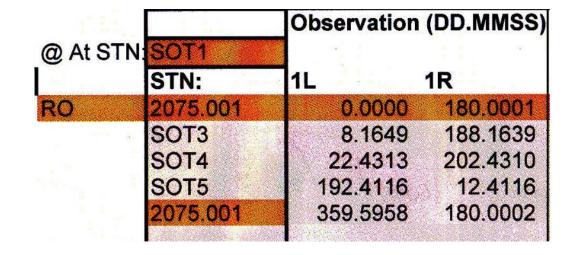


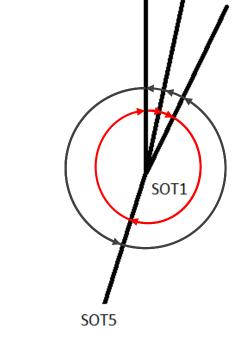


• 盘右,逆时针观测









2075.001

SOT3

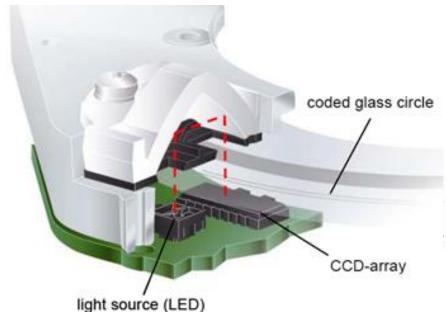
SOT4

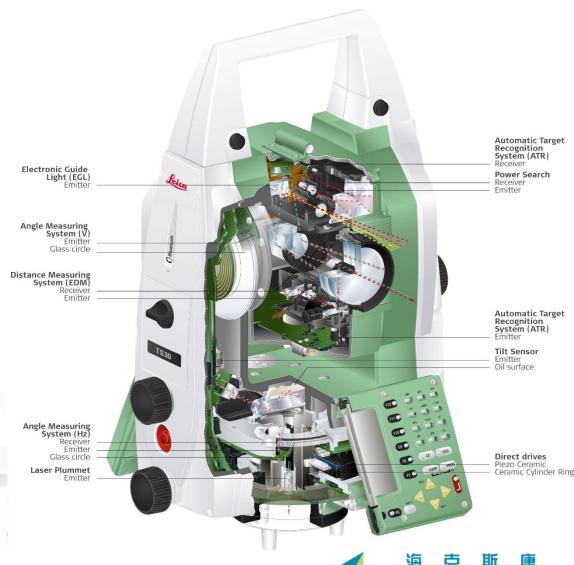
• 盘右,逆时针观测

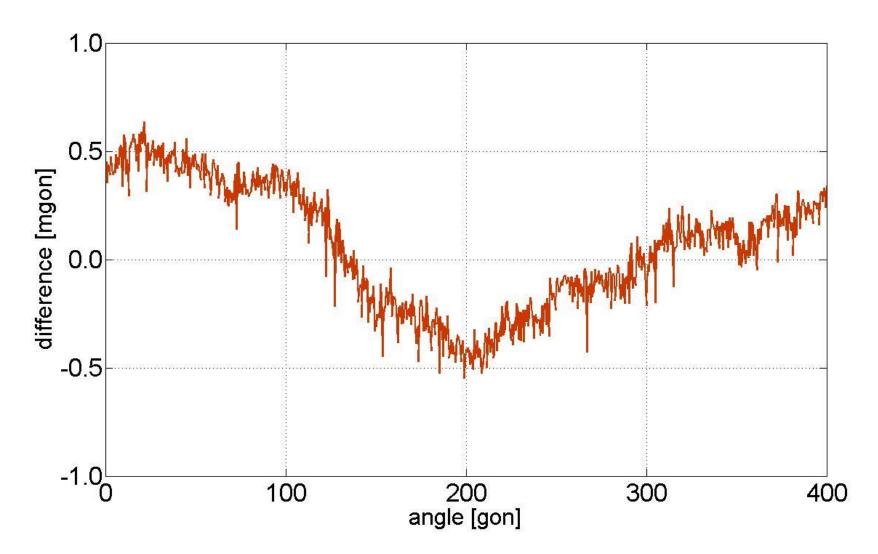


- ▶ 四角检测
 - 。4个编码器:消除进一步的π周期性误差
 - 。5000Hz,绝对,连续
 - 。精度提高约30%

$$\sigma_{4encoder} = \frac{1}{\sqrt{2}}\sigma_{2encoder}$$

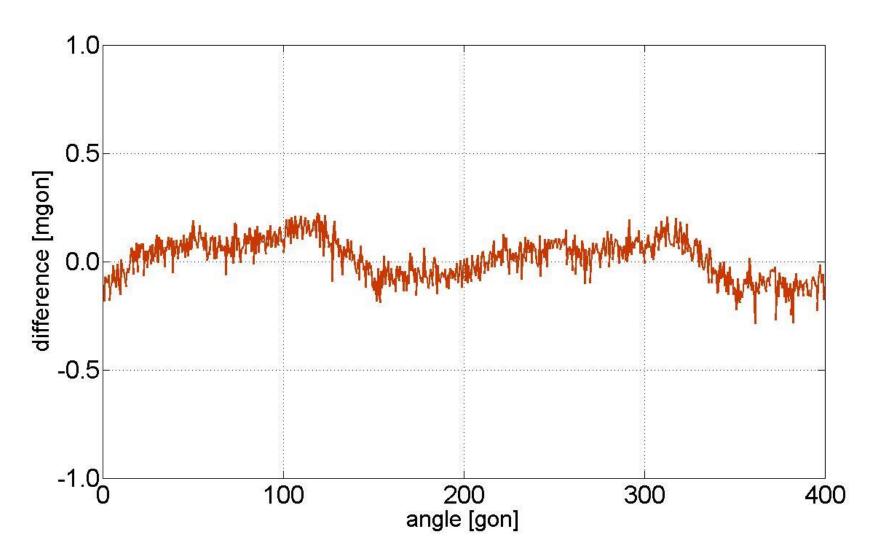






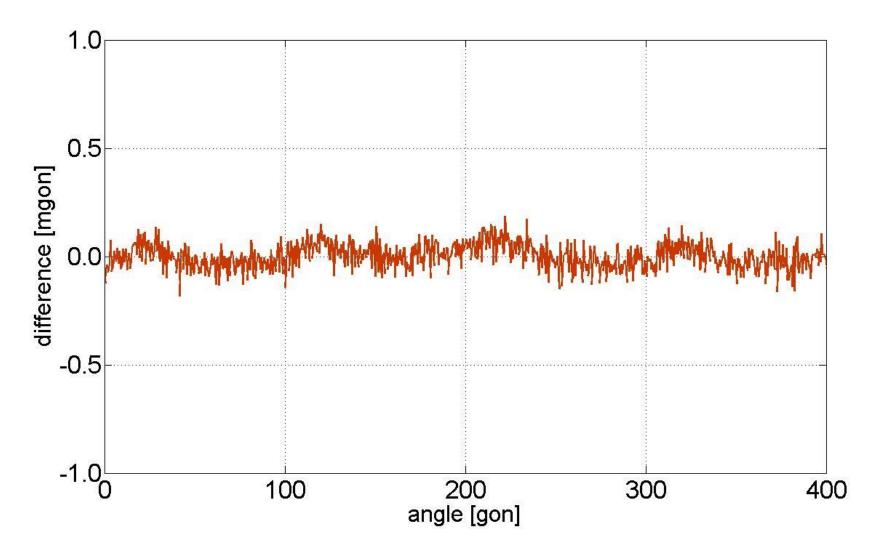
1 Encoder $\sigma = 0.981$ " (0.303mgon)





2 Encoder $\sigma = 0.301$ " (0.093mgon)





4 Encoder $\sigma = 0.203$ " (0.063mgon)



GNSS 参考站







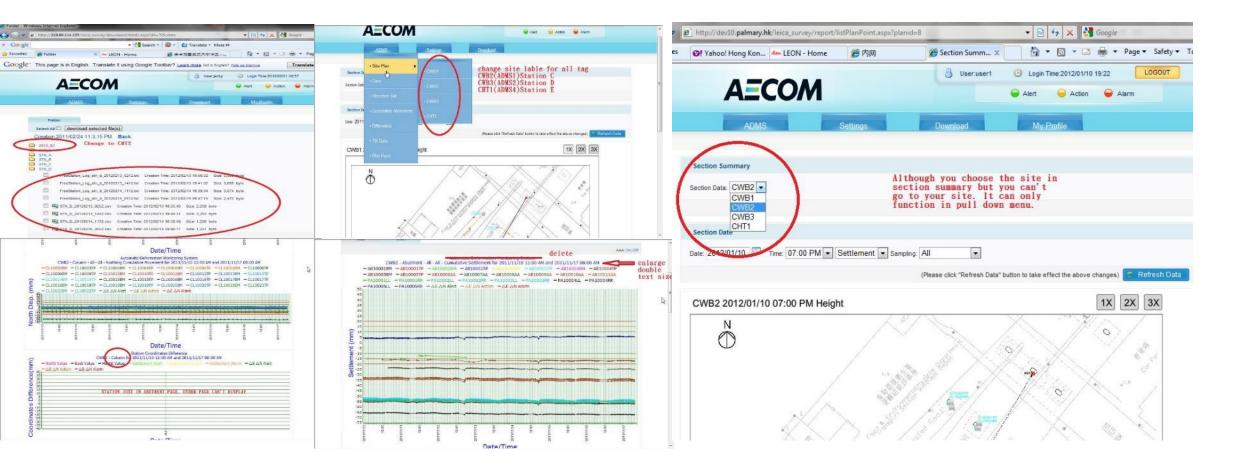
Nivel 监测







Web Interface





谢谢